

Automated Arrival Traffic Flow Management Using 4D Trajectories

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Detect the Difference

Outline

- Why 4D Trajectories?
- Mature State 4DT System
 - Components
 - Roles & Responsibilities
 - Benefits
 - Roadmap
- Potential 2007 4DT Experiment
 - Goals & Method
 - System Architecture
 - Roles & Procedures
 - Future Evolution
- Next Steps

4D Trajectories: A *Revolution* in ATM

Non-Radar Procedures



- Estimate Current Position
- Estimate Future Position

Radar Procedures



- Know Current Position
- Estimate Future Position

4D Trajectory Procedures



- Know Current Position
- Know Future Position



Why 4D Trajectories?

- A Future ATM System with
 - 4D Trajectory (4DT)-based FMS-equipped Aircraft, and
 - 4DT-based ATM Ground Automation

Means:

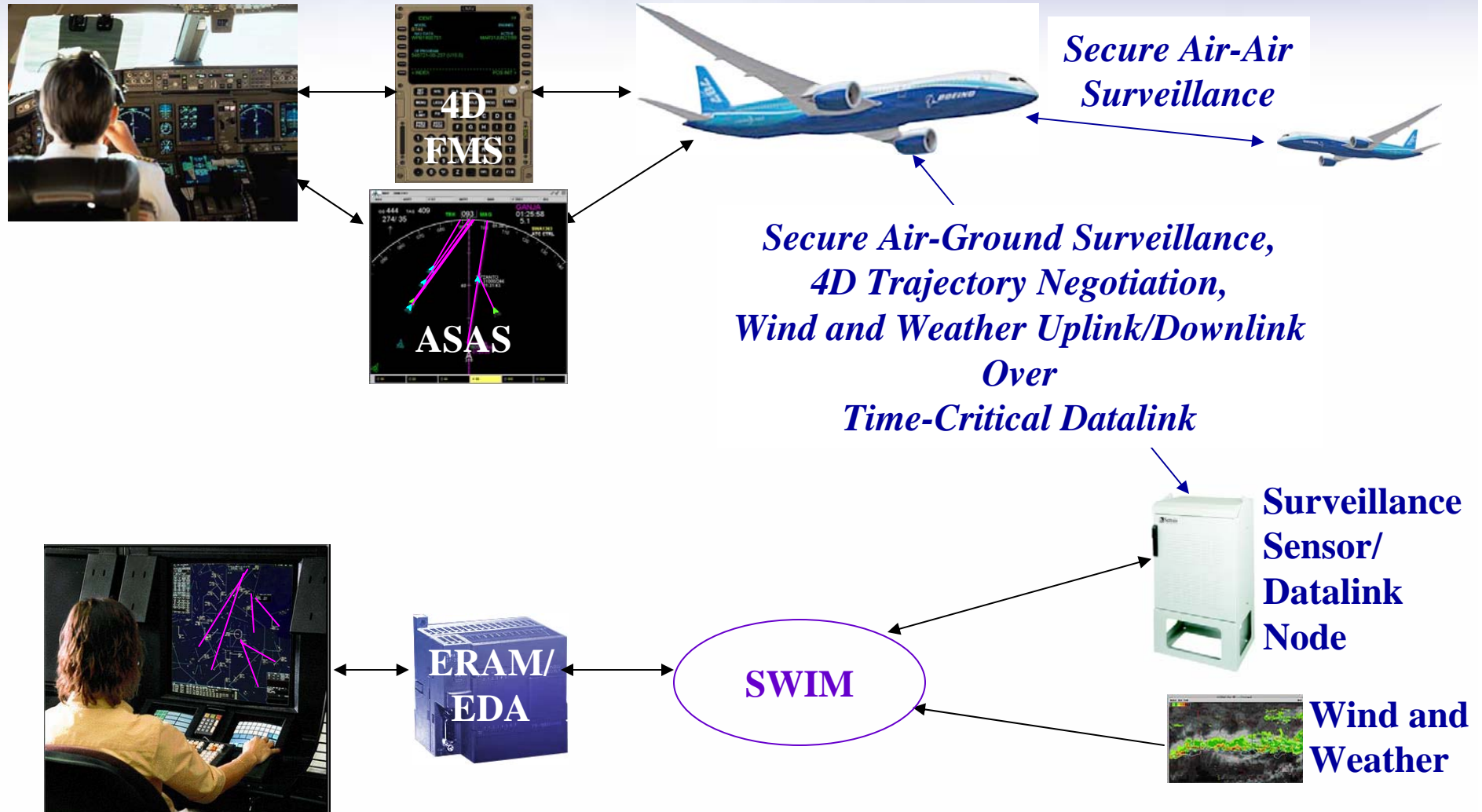
- Improved Air-Ground Coordination of Intent,
- Improved System Predictability,
- Improved Air Traffic Planning, and
- Reduced Flight Technical Error

Which Should Result in:

- Increased Situational Awareness
- Increased Safety
- Increased Capacity
- Improved ANSP Productivity
- Reduced Operating Costs, Fuel Burn, and Emissions

- Significant JPDO, Eurocontrol and Industry Interest in 4D Trajectory Research and Implementation
 - JPDO NGATS vision features 4DT-based operations
- *Need to show technical feasibility and operational viability*

Mature State 4D System



Logical Airborne vs. Ground Automation Roles and Responsibilities

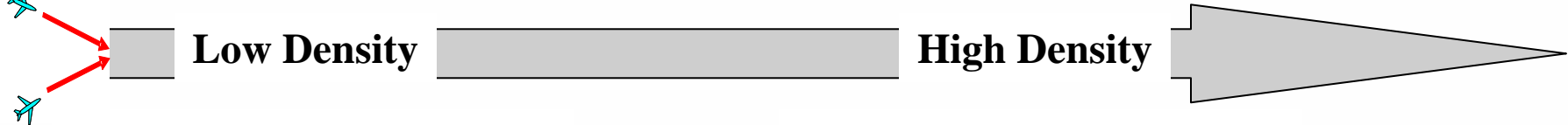


- *Generates and Downlinks User-Preferred Trajectory*
- *Generates and Downlinks Planned Trajectory*
- *Downlinks In-Situ Local Wind and Weather Information*



- *Determines Potential Conflicts*
- *Generates Conflict Resolutions*
- *Determines Time-Based Metering, when appropriate*
- *Determines and Uplinks Constraints to User-Preferred Trajectory*
- *Uplinks Wide-Area Wind and Weather Forecast Information*

Traffic Scenario



**Airborne Automation is
main driver of trajectory**

**Ground Automation is
main driver of trajectory**

4D Trajectory Negotiation: Benefits

Stakeholder	Benefits
Flight Crews (NAS Users) Air Transportation Providers: (AOC), Business, General and Military Aviation	Increased frequency and fidelity of accepted user preferences Reduced direct operating costs and improved schedule adherence
Air Navigation Service Provider/FAA	Reduced workload required to accept user preferences Reduced conflict-based corrective clearances through increased traffic predictability Greater airspace and airport capacity with reduced missed slots Greater motivation for airlines to equip with ADS-B and 4D FMS
Traveler and Shipper	Improved schedule adherence

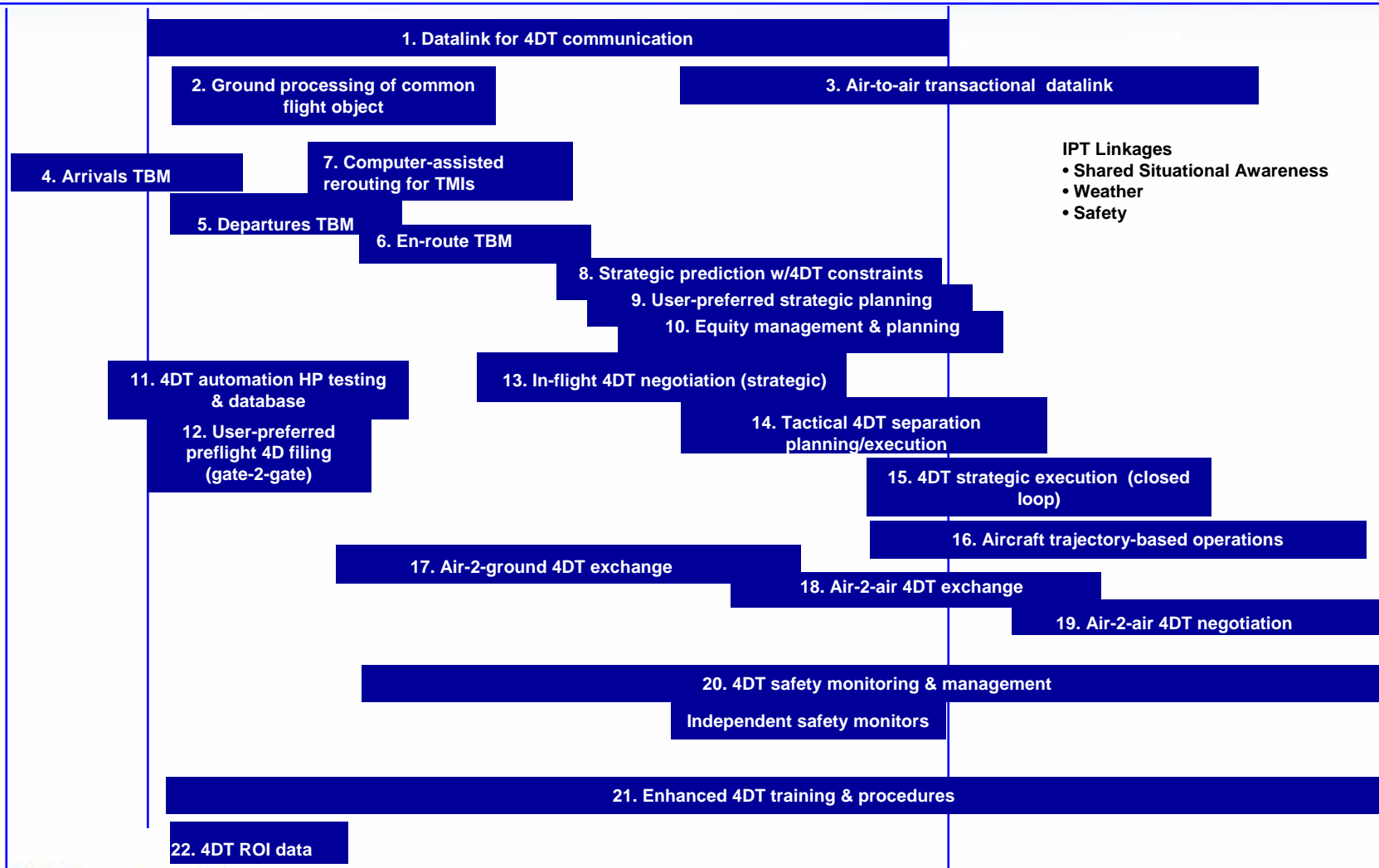
JPDO AATS Transformation Roadmap

Capability: 4D Trajectory Management

2006 2008

2016

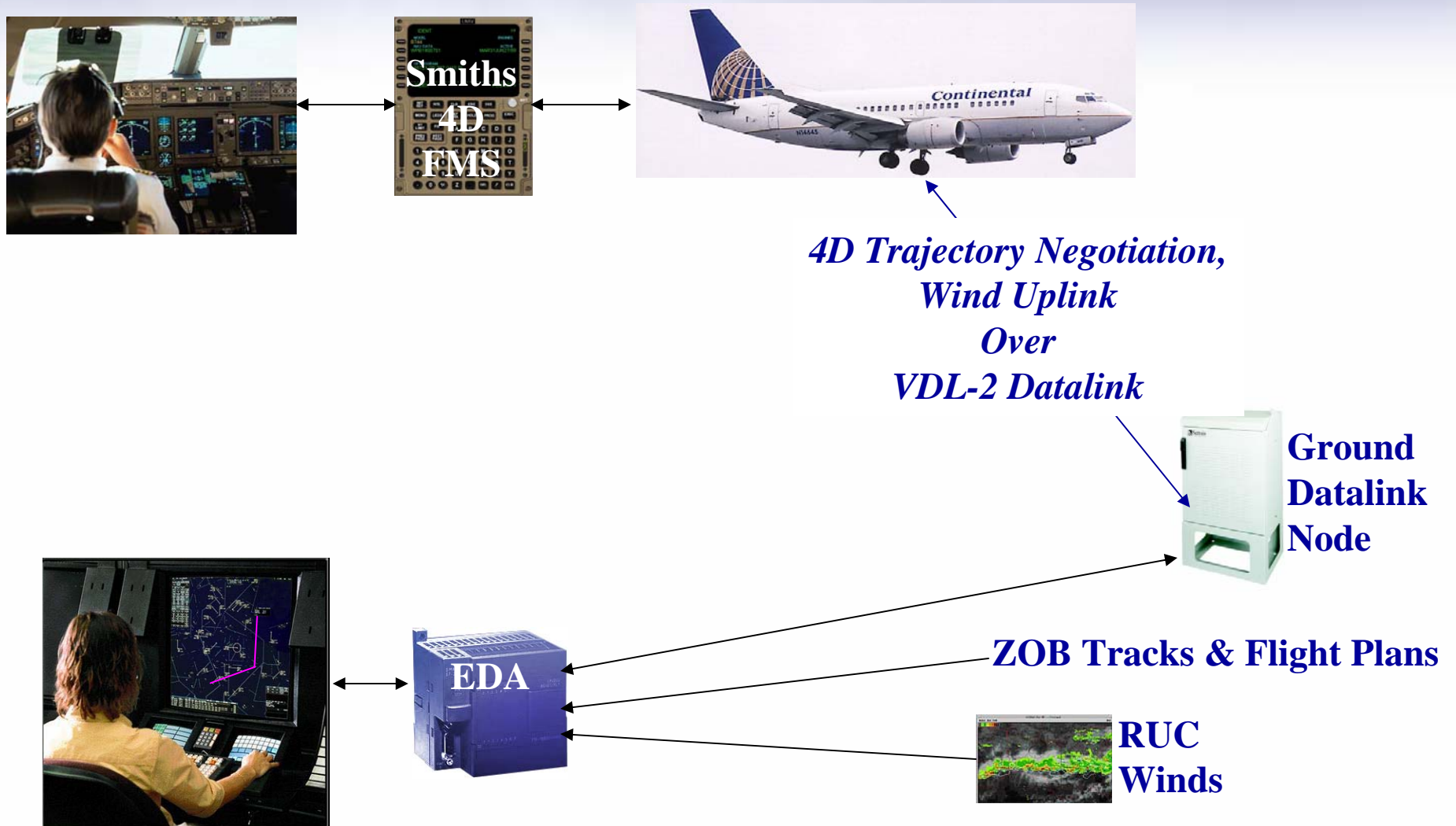
2025



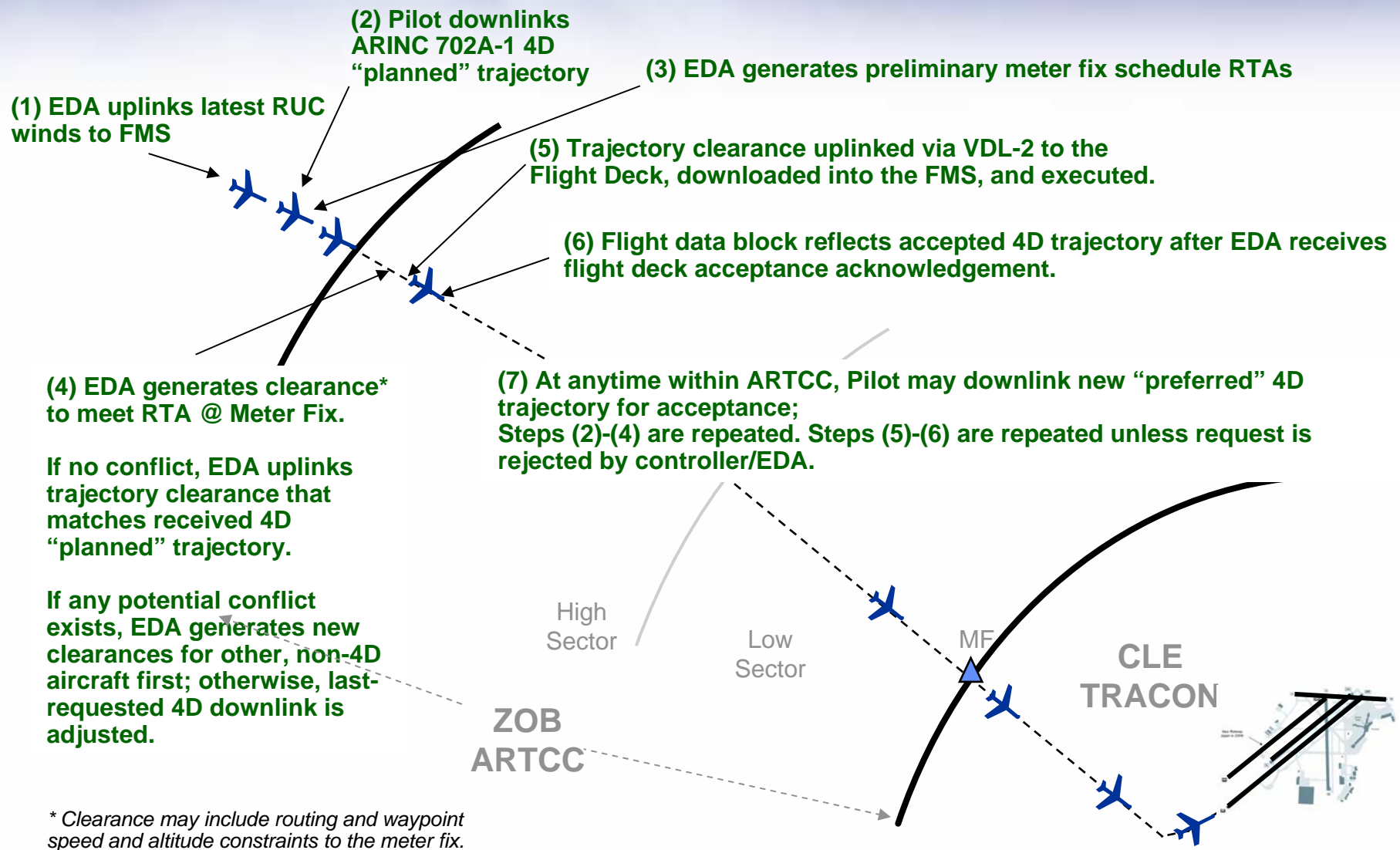
Scenario(s) / Experiment Planning: *Basic 4D En Route Experiment*

- **Goal:** Establish technical and operational feasibility of 4DT negotiation
- **Method:**
 - Conduct series of experiments on 4D FMS-equipped arrivals into KCLE.
 - Adapt and Use 4D-capable NASA EDA for trajectory negotiation with revenue-carrying 4D FMS-equipped aircraft.
- **Timeframe:** Experiments conducted Fall 2007
- **Intended Audience:** JPDO and Air Transportation Stakeholders
- **Required Govt/Industry Partners:** FAA, NASA, Airlines, Avionics Manuf's
- **Resources Needed:**
 - **Aircraft and Aircraft Equipage:**
 - One Aircraft, optional: additional aircraft
 - 4D FMS, optional: 3D FMS
 - VDL-2 Datalink Radio with interface to FMS and flight crew
 - **Ground Infrastructure:**
 - Real-time ZOB Track and Flight Plan Data, RUC Wind Data Feed
 - NASA 4D-Enabled En Route Descent Advisor (4D-EDA)
 - VDL-2 Ground Datalink Radio with interface to 4D-EDA and ANSP

4DT Experiment System Architecture



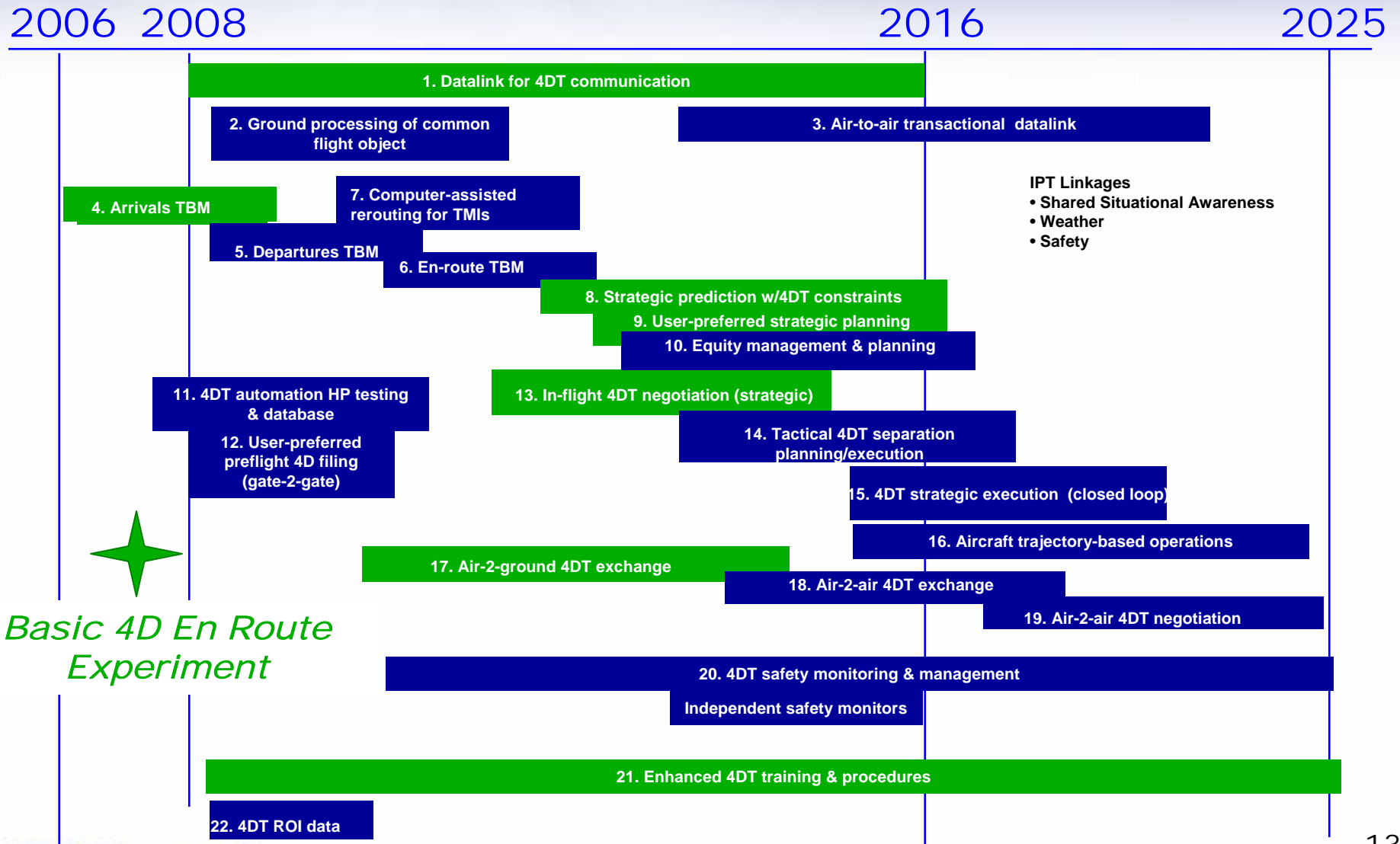
Simplified ARTCC 4D Trajectory Roles and Procedures



Key Expected Experiment Results

- A *Feasibility Assessment* of integrating 4D airborne and ground automation systems with current day flight deck layouts
- Identification and Assessment of key 4D contract negotiation factors
 - E.g., roles and tasks, pilot response time, accuracy of predicted trajectory
- A Quantification of real-world differences in:
 - Airborne and ground state and intent information,
 - Future trajectory predictions by airborne and ground-based trajectory predictors,
 - Closed-loop RTA adherence performance
- Recommendations for future 4DT system development and performance standards for:
 - Future aircraft and ground decision support systems, surveillance, and datalink performance

Sensis 4D Trajectory Experiment Addresses Multiple Steps in JPDO AATS Transformation Roadmap



Core Elements of a Series of 4D Trajectory Experiments

Airborne Automation



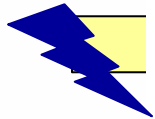
**4D Smiths FMS
ARINC 702A-1**

**4D Smiths FMS
ARINC 702A-3
+ 3D FMS**

**4D FMS + 3D FMS
+ Non-FMS**



Datalink



**Existing ACARS/
VDL-2**

**Time-Critical
Datalink**

**Time-Critical
Datalink**



Ground Automation



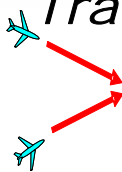
4D-EDA v1

**4D-EDA v2 +
4D-Terminal Descent Advisor**

**4D-EDA v3 +
4D-TDA v2
Incl. Wx**



Traffic Scenario



Low Density

High Density

**High Density
with Weather**



Why This and Why Now?

Why This Set of Experiments?

- According to JPDO, Use of 4D Trajectories is the “Coin of the Realm”
 - Expect significant airspace capacity improvements
 - Could be used to support “better-equipped, better-served” operations
- 4D FMSs and VDL-2 Datalink Exist on Revenue-Carrying Aircraft Today
 - Effort to Modify EDA to Be 4D-Compatible Should Not Be Prohibitive
- Getting out in the Operational Realm early will help flush out key op'l constraints early to minimize time-to-initial operating capability
 - Early and frequent exposure of new concepts to operational domain has been a hallmark of previous NASA successes
- Starting 4D research focused on a Single 4D En Route Aircraft avoids safety-critical issues and can offer potential benefits immediately

Why Now?

- Need to start NOW to develop and test 4D operations if we have a hope of implementing this within the next decade

Next Steps

- Investigating other concept options
 - Terminal Arrival 4DT
 - Departure 4DT
- Fleshing out details of 4D trajectory experiment architecture, and experiment plan
 - Working with Smiths and Rockwell-Collins to further understand 4DFMS and datalink limitations
- Looking for government and industry partnerships to make the 4DT concept a reality